

APACHE 4

AUTONOMOUS HYDROGRAPHIC
SURVEY USV



MARINE SURVEY
& CONSTRUCTION

ADVANCED NAVIGATION CONTROLLER

Integrated adaptive water flow straight -line and hovering technology

The autonomous control system enables APACHE 4 to navigate straight along the cross-section according to the profile view

The hovering technology can make APACHE 4 hover stably in the turbulent flow at the

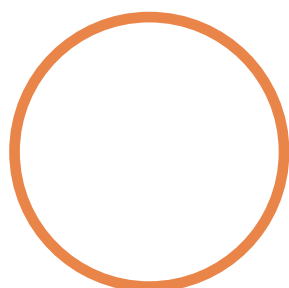
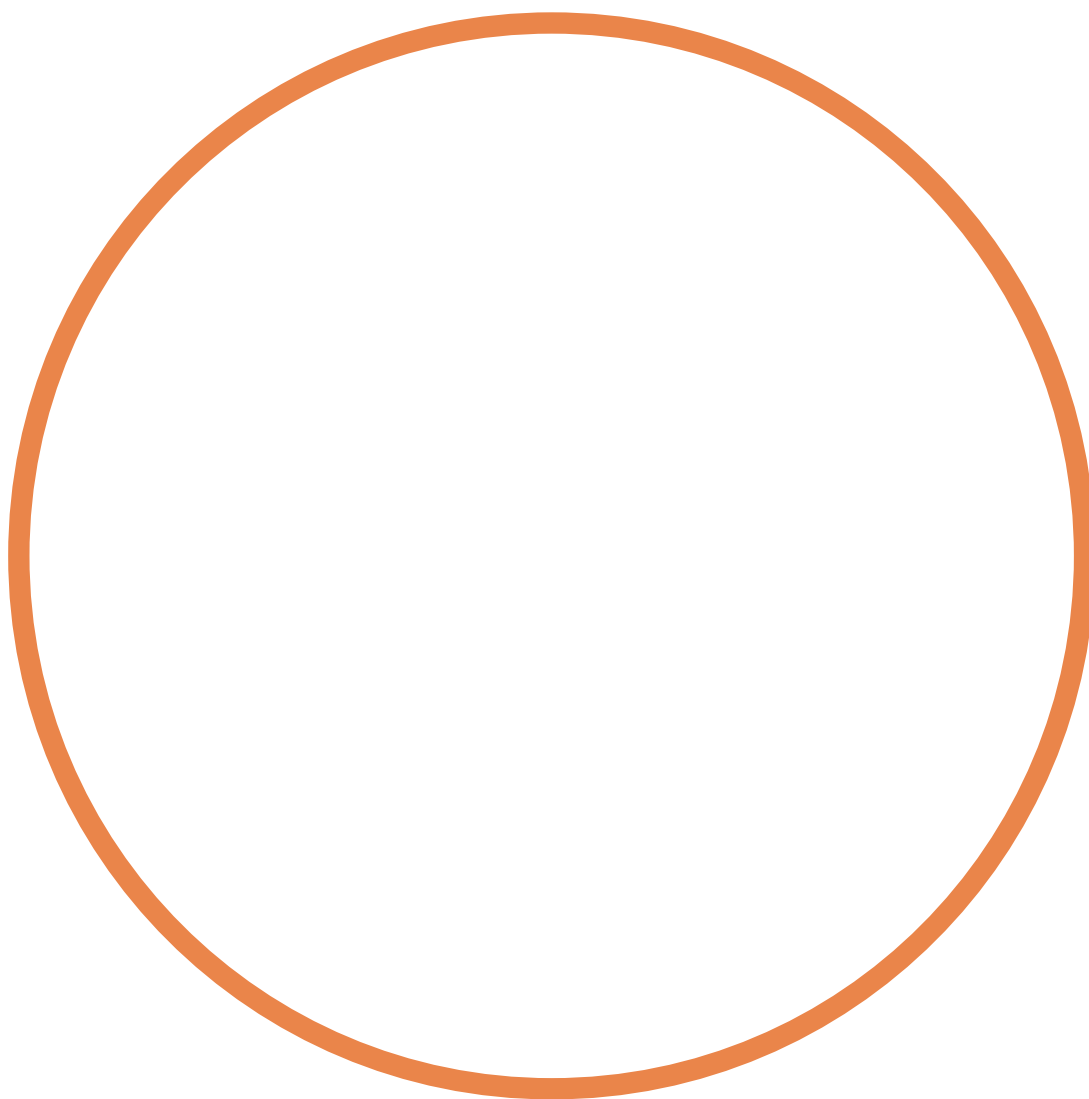
thereby improving the accuracy of flow

BUILT-IN SINGLE-BEAM ECHO SOUNDER

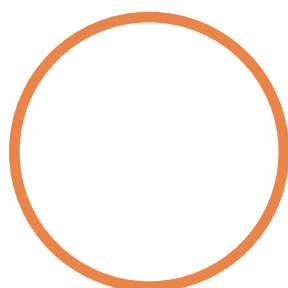
Single beam sounding data can be used to verify the accuracy of ADCP bottom tracking



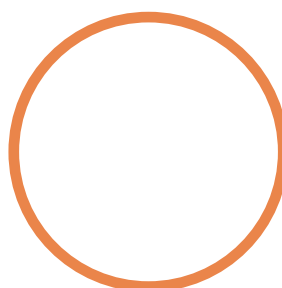
EFFICIENT HYDROGRAPHIC SURVEY USV



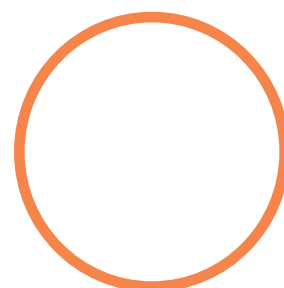
Millimeter wave radar



SBES Transducer



ADCP access shaft



Semi-embedded motor

SPECIFICATIONS

Physical
Hull dimension

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Anti-wave & Wind	rdnd wave level
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Hull design	Triple-hull vessel
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Water proof	
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Draft	
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	Two-color light
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Camera	
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ADCP Compatibility	navigable ADCP
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	ADCP and sounder are equipped at the
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Safe	
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distance	
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Power

Type	Electric
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Propeller type	
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Direction control	
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Li-ion battery capacity	
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	, support hot-
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Communication

Data communication	
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Interface

Navigation mode	
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Water proof of master control	
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Data storage	Local multi-sessions and FTP push
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Positioning

Satellite system	
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Channel	
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Single point position	
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accuracy	
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DGNSS positioning accuracy	
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accuracy	
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Heading accuracy	
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accuracy	
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D270 Single Beam Echo Sounder

Data type	CHCGD original waveform
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Weight	.
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Sounding range	
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Sounding accuracy	
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Frequency	
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Supply voltage	
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Waterproof	
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Software

Hydro Survey	post-processing support waveform
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Auro Planner	
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