

APACHE 4

AUTONOMOUS HYDROGRAPHIC
SURVEY USV



MARINE SURVEY
& CONSTRUCTION

ADVANCED NAVIGATION CONTROLLER

Integrated adaptive water flow straight -line and hovering technology

The autonomous control system enables APACHE 4 to navigate straight along the cross-section according to the profile view

The hovering technology can make APACHE 4 hover stably in the turbulent flow at the

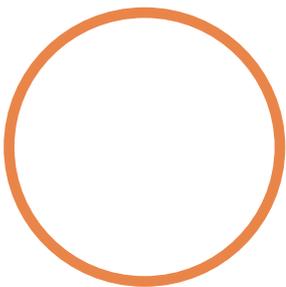
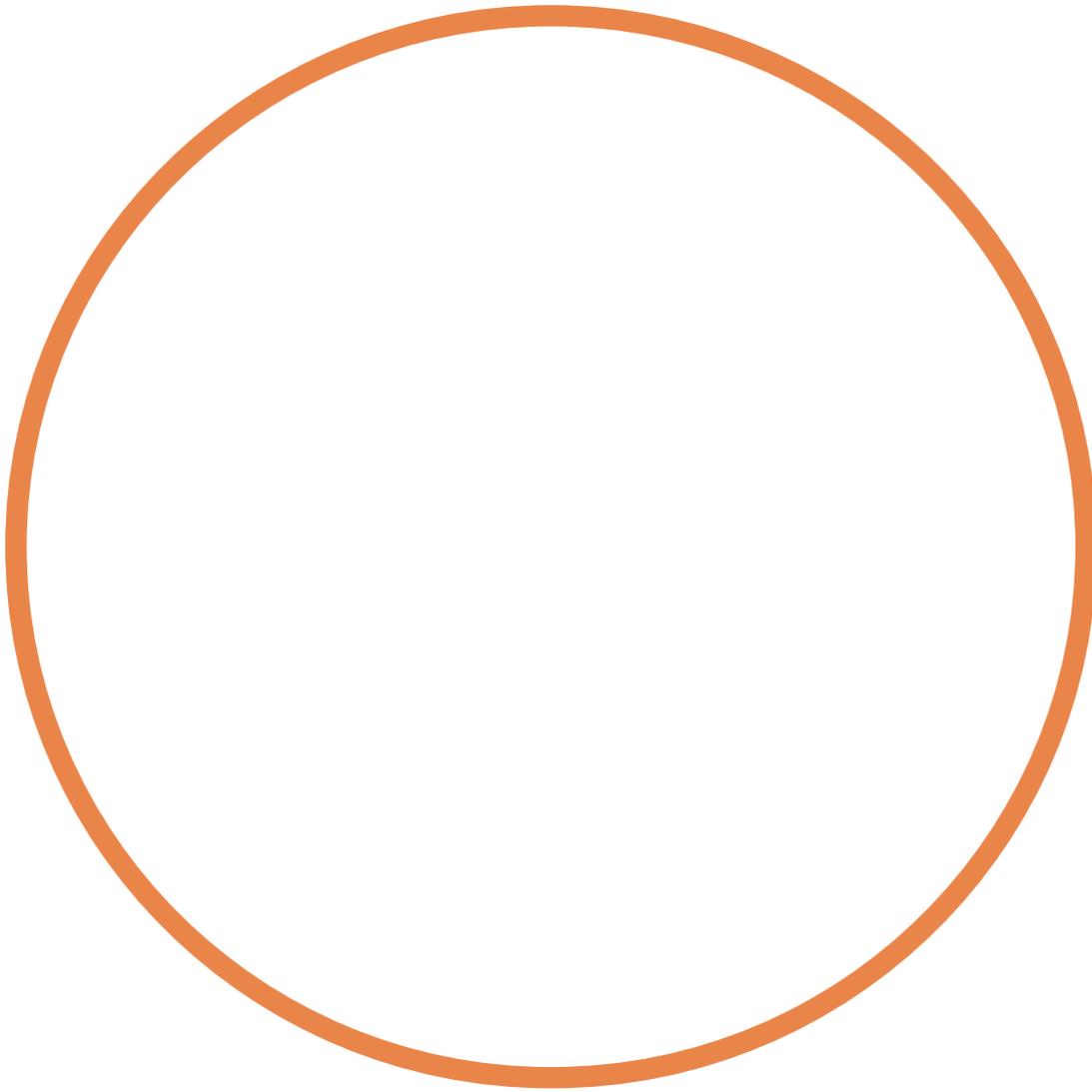
thereby improving the accuracy of flow

BUILT-IN SINGLE-BEAM ECHO SOUNDER

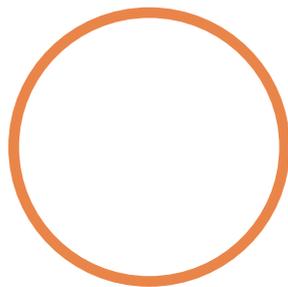
Single beam sounding data can be used to verify the accuracy of ADCP bottom tracking



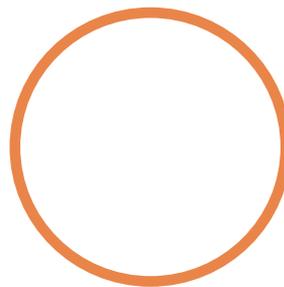
**EFFICIENT
HYDROGRAPHIC
SURVEY USV**



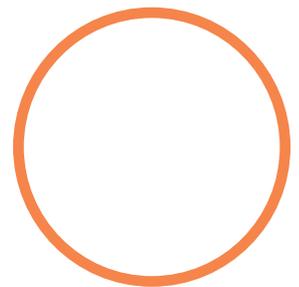
Millimeter wave radar



SBES Transducer



ADCP access shaft



Semi-embedded motor

SPECIFICATIONS

Physical

Hull dimension

Anti-wave & Wind rd nd wave level

Hull design Triple-hull vessel

Water proof

Draft

Two-color light

Camera

ADCP Compatibility

navigable ADCP

ADCP and sounder are equipped at the

Safe

distance

Power

Type Electric

Propeller type

Direction control

Li-ion battery capacity

, support hot-

Communication

Data communication

Interface

Navigation mode

Water proof of master control

Data storage

Local multi-sessions and FTP push

Positioning

Satellite system

Channel

Single point position

accuracy

DGNSS positioning accuracy

accuracy

Heading accuracy

accuracy

D270 Single Beam Echo Sounder

Data type

CHCGD original waveform

Weight

Sounding range

Sounding accuracy

Frequency

Supply voltage

Waterproof

Software

Hydro Survey

post-processing support waveform

Auro Planner

